PREPARE FOR EMERGENCIES

Be prepared if a fire starts.

Keep a first aid kit and fire extinguisher handy.

Keep emergency numbers for doctors, ambulance service, hospital, and fire department near your telephone.



PROTECT AGAINST FLYING DEBRIS

Guard against injury from flying pieces of metal or debris; Wear goggles or safety glasses.



PROTECT AGAINST NOISE

Prolonged exposure to loud noise can cause impairment or loss of hearing.

Wear a suitable hearing protective device such as earmuffs or earplugs to protect against objectionable or uncomfortable loud noises.



AVOID POWER LINES

Serious injury or death can result from contact with electric lines.

Never move any part of the machine or load closer to electric line than 3m(10ft) plus twice the line insulator length.



GROUP 2 SPECIFICATIONS

1. MAJOR COMPONENT



21072SP01A

7. UNDERCARRIAGE

1) TRACKS

X-leg type center frame is integrally welded with reinforced box-section track frames. The design includes dry tracks, lubricated rollers, idlers, sprockets, hydraulic track adjusters with shock absorbing springs and assembled track-type tractor shoes with triple grousers.

2) TYPES OF SHOES

	Shapes		Triple grouser			
Model						
R210LC-7	Shoe width	mm(in)	600(24)	700(28)	800(32)	-
	Operating weight	kg(lb)	21700(47840)	21980(48460)	22270(49100)	-
	Ground pressure	kgf/cm²(psi)	0.46(6.54)	0.40(5.69)	0.35(4.98)	-
	Overall width	mm(ft-in)	2990(9' 10")	3090(10' 2")	3190(10' 6")	-
R210LC-7 LONG REACH	Shoe width	mm(in)	-	-	800(32)	-
	Operating weight	kg(lb)	-	-	24360(53700)	-
	Ground pressure	kgf/cm²(psi)	-	-	0.42(5.97)	-
	Overall width	mm(ft-in)	-	-	3190(10' 6")	-
R210LC-7 HIGH WALKER	Shoe width	mm(in)	600(24)	700(28)	800(32)	Double grouser 710(28)
	Operating weight	kg(lb)	23160(51060)	23440(51680)	23730(52320)	23770(52400)
	Ground pressure	kgf/cm ² (psi)	0.49(6.97)	0.43(6.12)	0.38(5.40)	0.43(6.12)
	Overall width	mm(ft-in)	3395(11' 2")	3495(11' 6")	3595(11' 10")	3505(11' 6")

3) NUMBER OF ROLLERS AND SHOES ON EACH SIDE

Item	Quantity
Carrier rollers	2EA
Track rollers	9EA
Track shoes	49EA

Flow reducing function



As the pilot pressure Pi rises, the pilot piston(643) moves to the right to a position where the force of the pilot spring(646) balances with the hydraulic force.

The groove(A) in the pilot piston is fitted with the pin(875) that is fixed to lever 2(613). Therefore, when the pilot piston moves, lever 2 rotates around the fulcrum of point B [fixed by the fulcrum plug(614) and pin(875)]. Since the large hole section(C) of lever 2 contains a protruding pin(897) fixed to the feedback lever(611), the pin(897) moves to the right as lever 2 rotates. Since the opposing-flat section(D) of the feedback lever is fitted with the pin(548) fixed by the tilting pin(531) that swings the swash plate, the feedback lever rotates around the fulcrum of point D, as the pin(897) moves.

Since the feedback lever is connected with the spool(652) via the pin(874), the spool moves to the right.

The movement of the spool causes the delivery pressure P1 to connect to port CL through the spool and to be admitted to the large diameter section of the servo piston. The delivery pressure P1 that is constantly admitted to the small diameter section of the servo piston moves the servo piston to the right due to the area difference, resulting in decrease of the tilting angle.

When the servo piston moves to the right, point D also moves to the right. The spool is fitted with the return spring(654) and is tensioned to the left at all times, and so the pin(897) is pressed against the large hole section(C) of lever 2.

Therefore, as point D moves, the feedback lever rotates around the fulcrum of point C, and the spool is shifted to the left. This causes the opening between the sleeve(651) and spool(652) to close slowly, and the servo piston comes to a complete stop when it closes completely.

2. FUNCTION

1) ROTARY PART

When high pressurized oil enters a cylinder through port(a), which is the inlet of balance plate(1), hydraulic pressure acting on the piston causes axial force F. The pressure force F works via the piston(2) upon the return plate(3) which acts upon the swash plate(4) via an hydrostatic bearing. Force F1 perpendicular to swash plate(4) and force F2 perpendicular to cylinder center.

Being transferred to the cylinder block(5) through piston, force F2 causes rotational moment at surroundings of cylinder.

Since cylinder block has 9 equidistantly arrayed pistons, rotational torque is transmitted to cylinder shaft in order by several pistons connected to the inlet port of high pressurized oil. When the direction of oil flow is reversed, rotational direction of cylinder is also reversed. Output torque is given by the equation.

$$T = \frac{p \times q}{2}, q = Z \cdot A \cdot PCD \cdot tan , F1 = \frac{F}{COS}, F_2 = F tan , S = PCD \times tan$$

Where p: Effective difference of pressure(kgf/cm²)

- q : Displacement(cc/rev)
- T: Output torque(kgf · cm)
- Z : Piston number(9EA)
- A : Piston area(cm²)
 - : Tilting angle of swash plate(degree)
- S : Piston stroke(cm)



3) OPERATION

The operation of the pilot valve will be described on the basis of the hydraulic circuit diagram shown below and the attached operation explanation drawing.

The diagram shown below is the typical application example of the pilot valve.



- 1 Pilot valve
- 2 Pilot pump
- 3 Main pump
- 4 Main control valve
- 5 Hydraulic motor
- 6 Hydraulic cylinder

2. CONNECTION TABLE FOR CONNECTORS

1) PA TYPE CONNECTOR



GROUP 12 PROLIX SWITCH (up to # 0179)

Is the conversion switch to manual control temporarily when the electronic control system is out of order, until repair work be done.



1. OPERATING PRINCIPLE WIRING DIAGRAM



21075MS17

1) NORMAL POSITION

 EPPR valve supply specified amount of pilot pressure to the flow regulator of hydraulic pump and regulate hydraulic pump delivery amount depending upon the signal of CPU controller by selected mode.

2) EMERGENCY POSITION

- If prolix switch is set at the emergency position when any abnormality occurs in NEW CAPO system, constant electric current from battery flows to EPPR valve so that EPPR valve can be fixed at the predetermined position.
- · In this case excavator can be operated at an equivalent performance to S mode.

3) CAVITATION OCCURS WITH PUMP



4) HYDRAULIC OIL IS CONTAMINATED



3. ENGINE STALL(up to #0179)

Before carrying out below procedure, check all the related connectors are properly inserted.

1) INSPECTION PROCEDURE



Wiring diagram



29076MS01

3. SWING DEVICE

Part name	Inspection item	Remedy
Balance plate	 Worn less than 0.03mm Worn more than 0.03mm Sliding surface has a seizure(Even through small). 	 Lapping Replacement
Shoe of piston assembly	 Sliding surface has a damage. Sliding surface depression() dimension less than 0.45mm or has a large damage. 	 Replacement Lapping Replace parts or motor
Piston of piston assembly	 Sliding surface has a seizure(Even though small). 	Replace motor
Piston hole of cylinder assembly	 Sliding surface has a seizure. Sliding surface has a damage. 	 Replace motor Replace motor
Taper roller bearing Needle bearing Roller bearing	In case 3000hour operation.Rolling surface has a damage.	 Replacement Replacement

GROUP 3 PUMP DEVICE

1. REMOVAL AND INSTALL

1) REMOVAL

- (1) Lower the work equipment to the ground and stop the engine.
- (2) Operate the control levers and pedals several times to release the remaining pressure in the hydraulic piping
- (3) Loosen the breather slowly to release the pressure inside the hydraulic tank.
- Escaping fluid under pressure can penetrate the skin causing serious injury.
- (4) Loosen the drain plug under the hydraulic tank and drain the oil from the hydraulic tank.
 - Hydraulic tank quantity : 180
- (5) Remove socket bolts(74) and disconnect pipe(9).
- (6) Disconnect pilot line hoses(4, 5, 6, 7, 8, 9).
- (7) Remove socket bolts(72) and disconnect pump suction tube(3).

When pump suction tube is disconnected, the oil inside the piping will flow out, so catch it in oil pan.

(8) Sling the pump assembly and remove the pump mounting bolts.

· Weight : 120kg(265lb)

Pull out the pump assembly from housing. When removing the pump assembly, check that all the hoses have been disconnected.







2. MAIN PUMP(1/2)

1) STRUCTURE



114 Spline coupling 123 Roller bearing 124 Needle bearing 127 Bearing spacer 141 Cylinder block 151 Piston 152 Shoe 153 Set plate 156 Bushing 157 Cylinder spring 158 Spacer 211 Shoe plate 212 Swash plate

Bushing

214

- 312 Valve block 313 Valve plate(R) 314 Valve plate(L) 401 Hexagon socket bolt 406 Hexagon socket bolt 466 VP Plug 468 **VP** Plug 490 Plug 531 Tilting pin 532 Servo piston 534 Stopper(L) 535 Stopper(S)
- 548 Pin
- 702 O-ring

- 725 O-ring 728 O-ring 732 O-ring 774 Oil seal 789 Back up ring 792 Back up ring 806 Hexagon head nut 808 Hexagon head nut 824 Snap ring 885 Pin Spring pin 886 901 Eye bolt
- 953 Set screw
- 954 Set screw

2. DISASSEMBLY AND ASSEMBLY OF SWING MOTOR

1) STRUCTURE





21072SF04

- 1 Inner ring
- 2 Oil seal
- 3 Taper roller bearing
- 4 Backing spring
- 5 Cam plate
- 6 Return plate
- 7 Piston assembly
- 8 Lining plate
- 9 Plate
- 10 O-ring
- 11 Piston
- 12 O-ring
- 13 Spring
- 14 Parallel pin
- 15 Piston

- 16 Cap
- 17 O-ring
- 18 Coned disc spring
- 19 Teflon ring
- 20 Bushing
- 21 Balance plate
- 22 Needle bearing
- 23 Snap ring
- 24 Cylinder
- 25 Housing
- 26 Collar
- 27 Plug
- 28 Snap ring
- 29 Bypass valve assembly
- 30 Back up ring

- 31 O-ring
- 32 O-ring
- 33 Cover
- 34 Relief assembly
- 35 O-ring
- 36 Hexagon socket bolt
- 37 Time delay valve
- 38 O-ring
- 39 O-ring
- 40 Hexagon socket bolt
- 41 Check
- 42 Spring
- 43 Cap
- 44 Back up ring

- ⑦ Spreading grease on valve plate(24), assemble into rear cover(21).
 - \cdot Valve plate $\times 1 \text{EA}$



078SM212/212A

⑧ Lift up rear cover assy on body(1) by a crane and assemble it with a wrench bolt(27).

③ Assemble level gauge(44) into body(1).





14078SM202/202A

14078SM203/203A

① Assemble time delay valve assy(35) into rear cover(21) with a wrench bolt(36).



14078SM01/201A